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Local Search and Reactive Search Optimization (RSO)

Everybody carries on his shoulders the responsibility of his choices. It is a nice weight.
(Romano Battiti)



Brute force is not the solution

- Let's assume that one has to find the minimum of a discrete (combinatorial) optimization problem (for example, think about the *travelling salesman* problem)
- Evaluating all possible combinations of inputs can be computationally impossible
- One needs to resort to clever techniques to solve these problems

Local search based on perturbations

- starting from an **initial tentative solution**
- try to **improve it through repeated small changes**
- **stop** when **no improving local change exists**
(**local optimum**, or locally optimal point)

Local search optimization: notation

- \mathcal{X} is the search space
- $X^{(t)}$ is the current solution at iteration t .
- $N(X^{(t)})$ is the neighborhood of point $X^{(t)}$, obtained by applying a set of basic moves μ_0, \dots, μ_M to the current configuration

$$N(X^{(t)}) = \{X \in \mathcal{X} \text{ such that } X = \mu_i(X^{(t)}), i = 0, \dots, M\}.$$

Local search optimization

- Local search starts from an admissible configuration $X^{(0)}$ and builds a trajectory $X^{(0)}, \dots, X^{(t+1)}$.
- The successor of the current point is constructed as follows

$$Y \leftarrow \text{IMPROVING-NEIGHBOR}(N(X^{(t)}))$$
$$X^{(t+1)} = \begin{cases} Y & \text{if } f(Y) < f(X^{(t)}) \\ X^{(t)} & \text{otherwise (search stops).} \end{cases}$$

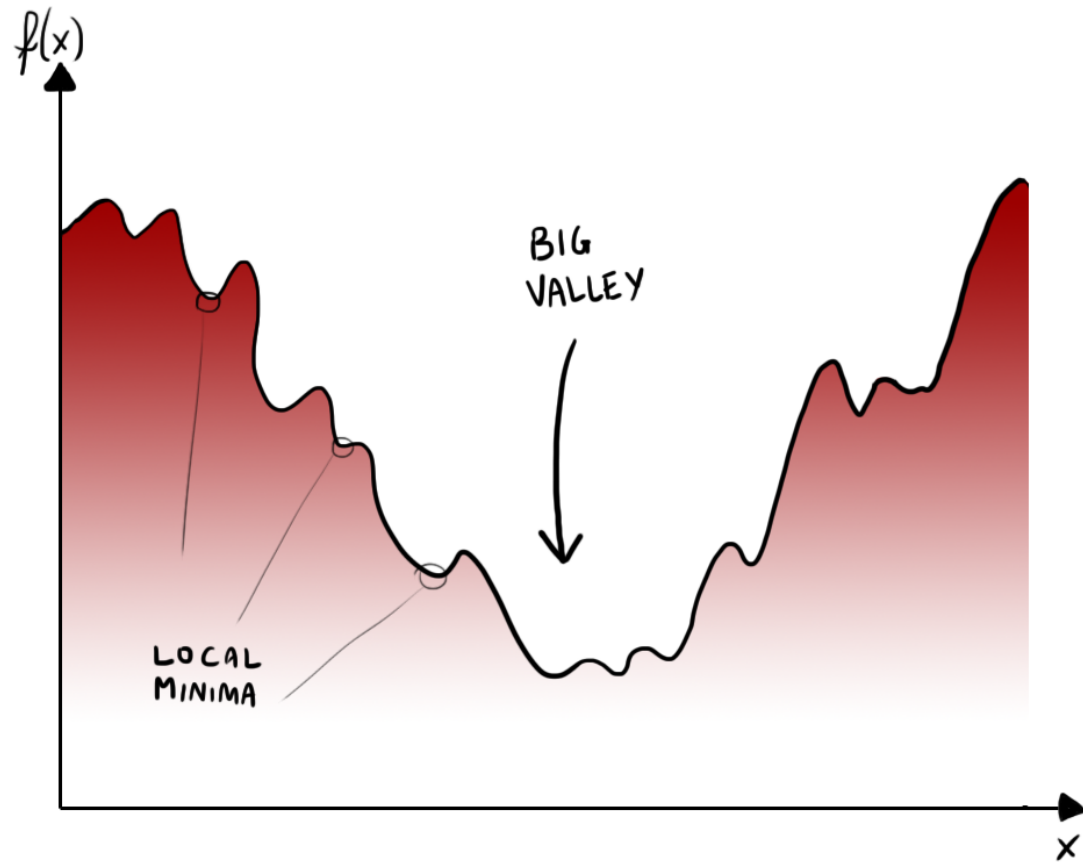
- IMPROVING -NEIGHBOR returns **an improving element in the neighborhood**

Local optima are not always global optima

- For many optimization problems, a closer approximation to the global optimum is required
- More complex search schemes have to be adopted to balance in an optimal way **exploration** and **exploitation**

Attraction basins

- **Local minima tend to be clustered** (good local minima tend to be closer to other good minima)
- The **attraction basin** associated with a local optimum is the set of points X which are mapped to the given local optimum by the local search trajectory
- if local search stops at a local minimum, **kicking** the system to a close attraction basin can be much more effective than restarting from a random configuration



Structure in optimization problems: the “big valley” hypothesis.

Modifications of local search based on perturbations

- local search by small perturbations is an effective technique but additional ingredients are in certain cases needed to obtain superior results



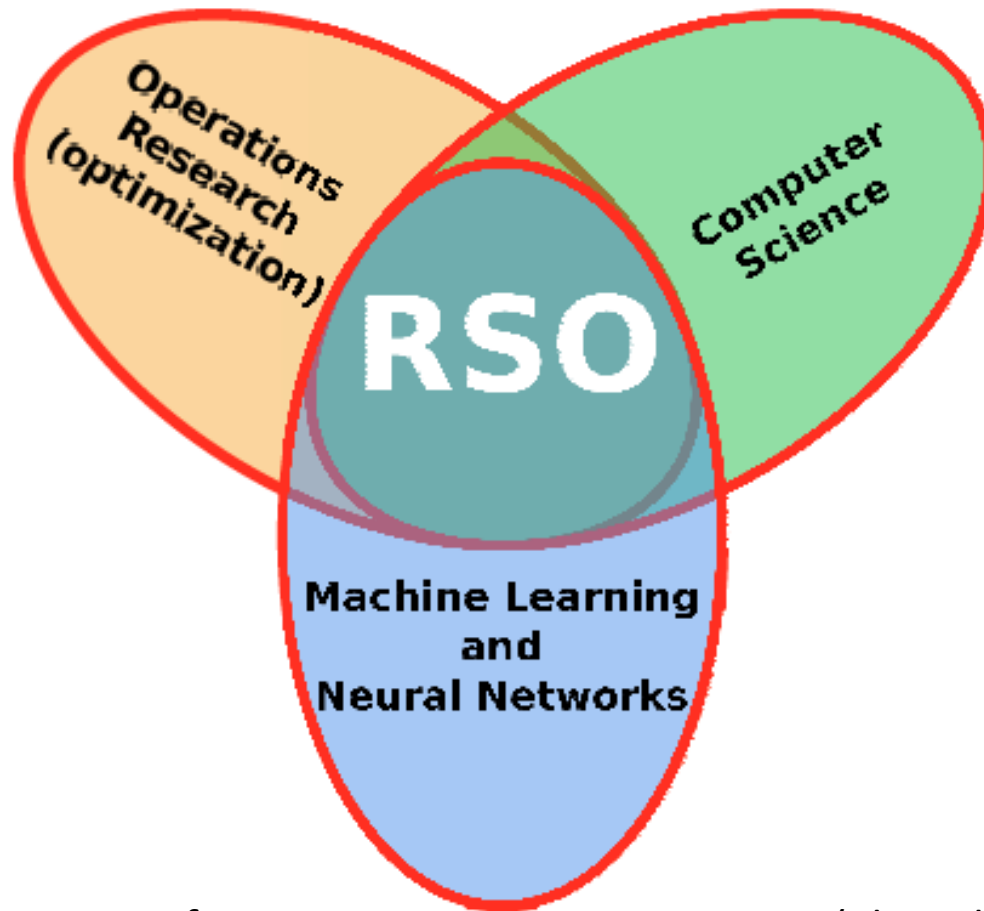
Local search in action: how to build a better bike, from the initial model (left) to a worse variation (middle), to the final and better configuration (right).

Reactive Search Optimization (RSO): Learning while searching

- Many problem-solving methods are characterized by a certain number of choices and free parameters, usually manually tuned.
- **Parameter tuning can be automated** as a part of the optimization algorithm
- This leads to self-contained, fully automated algorithms, independent from human intervention

Reactive Search Optimization (RSO) integrates **online machine learning techniques and search heuristics** for solving complex optimization problems.

Reactive Search Optimization (RSO):



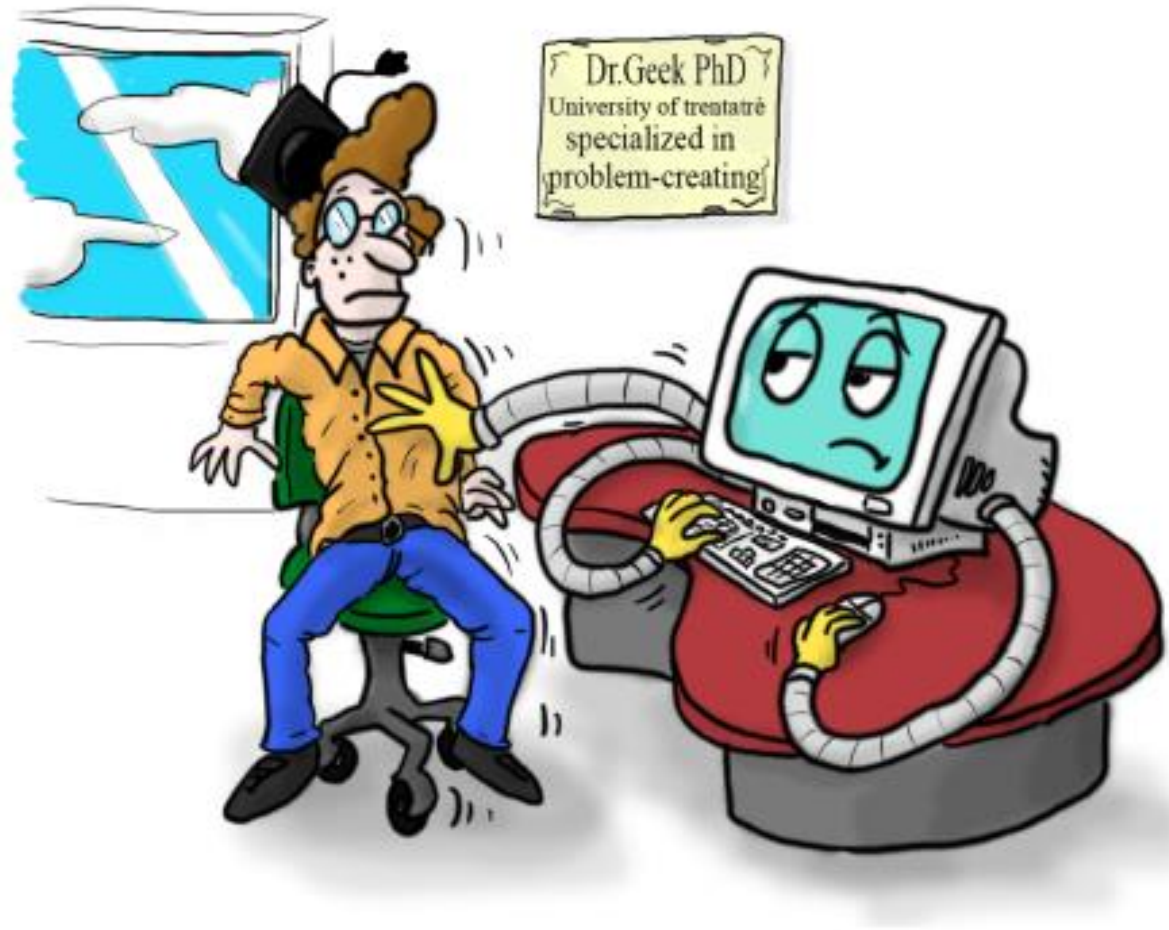
RSO is the intersection of optimization, computer science (algorithms and data structures) and machine learning.

Reactive Search Optimization

- RSO can be applied to systems that require to set some operating **parameters** to improve its functionality.
- A simple loop is performed: set the parameters, observe the outcome, then change the parameters in a strategic and intelligent manner until a suitable solution is identified
- In order to operate efficiently, RSO uses **memory and intelligence to improve solutions in a directed and focused manner**

Reactive Search Optimization

- While many alternative solutions are tested in the exploration of a search space, patterns and regularities appear
- The human brain quickly learns and drives future decisions based on previous observations.
- This is the main inspiration source for inserting online machine learning techniques into the optimization engine of RSO



Algorithms with **self-tuning** capabilities like RSO make life simpler for the final user. Complex problem solving does not require technical expertise but is available to a much wider community of final users

RSO based on prohibitions: tabu search

- Basic idea: using **prohibitions to encourage diversification**

How?

- While constructing a trajectory for local minima search, every time a move is applied, **the inverse move is temporarily prohibited**

Tabu search: an example

- Let $\chi = \{0,1\}^L$
- The neighborhood is obtained by applying the elementary moves μ_i , ($i = 1, \dots, L$) that change the i -th bit of the string $X = [x_1, \dots, x_i, \dots, x_L]$
- At each step, the selected move is the one that minimizes the target f in the neighborhood even if f increases, to exit from local minima.
- As soon as a move is applied, **the inverse move is temporarily prohibited**

Tabu search

- Tabu search can generate cycles. For example, if the current point $X^{(t)}$ is a strict local minimum
- In general, the inverses of the moves executed in the most recent part of the search are prohibited for a period T , in order to avoid cycles and to diversify

Prohibition and diversification

- Let $H(X, Y)$ be the Hamming distance between two strings X and Y
- if only allowed moves are executed, and T satisfies $T < (n - 2)$ (at least two moves are allowed at each iteration), then
- The Hamming distance H between a starting point and successive points along the trajectory is strictly increasing for $T + 1$ steps:

$$H(X^{(t+\tau)}, X^{(t)}) = \tau \quad \text{for } \tau \leq T + 1.$$

- The minimum repetition interval R along the trajectory is $2(T + 1)$:

$$X^{(t+R)} = X^{(t)} \Rightarrow R \geq 2(T + 1).$$

Prohibition and diversification(2)

prohibition is related to the amount of diversification :

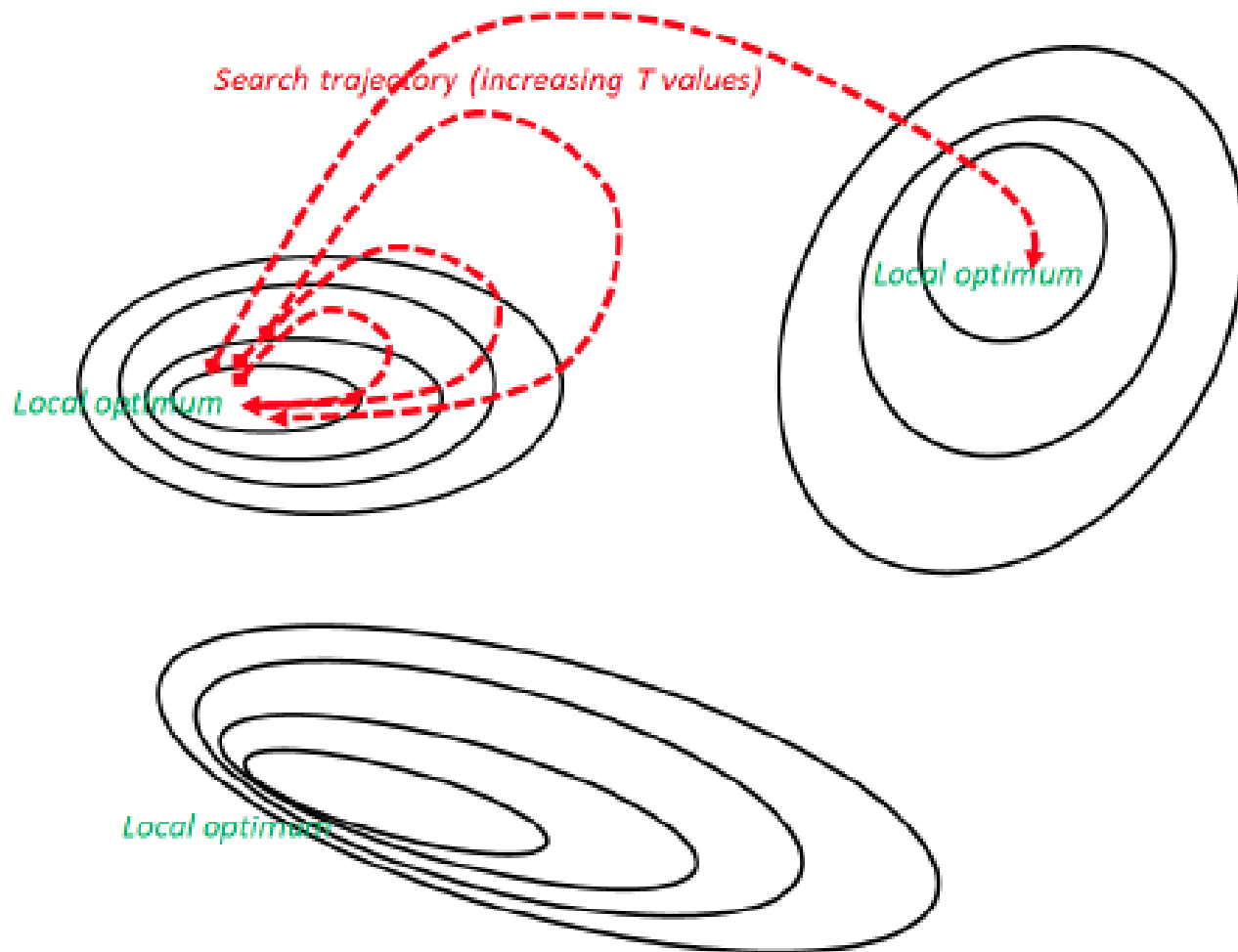
- the larger T , the larger is the distance H that the search trajectory must travel before it is allowed to come back
- If T is too large, the number of allowed moves will shrink, leading to less freedom of movement.

Iteration t	$X^{(t)}$	$f(X^{(t)})$	$H(X^{(t)}, X^{(0)})$
0	0 0 0 0 0 0 0 0	0	0
1	0 0 0 0 0 0 0 1	1	1
2	0 0 0 0 0 0 1 1	3	2
3	0 0 0 0 0 1 1 1	7	3
$T+1 \rightarrow$ 4	0 0 0 0 1 1 1 1	15	4
5	0 0 0 0 1 1 1 0	14	3
6	0 0 0 0 1 1 0 0	12	2
7	0 0 0 0 1 0 0 0	8	1
$2(T+1) \rightarrow$ 8	0 0 0 0 0 0 0 0	0	0

An example of the relationship between prohibition T , and diversification measured by the Hamming distance $H(X(t); X(0))$. $T = 3$ in the example

Tuning the T parameter

- The parameter T should be tailored to the specific problem
- BUT the choice of a **fixed T** without a priori knowledge is difficult
- RSO uses a simple mechanism to **change T during the search** so that the value $T^{(t)}$ is appropriate to the local structure of the problem
- RSO determines the minimal prohibition value which is sufficient to escape from an attraction basin around a minimizer



RSO with prohibitions in action. Three locally optimal points are shown together with contour lines of the function to be optimized. When starting from a locally optimal point, RSO executes loops which reach bigger and bigger distances from the attractor, until another attraction basin is encountered (if present).

RSO for tabu search

- T is equal to one at the beginning
- T **increases** if the trajectory is trapped in an attraction basin
- T **decreases** if unexplored search regions are visited, leading to different local optima

RSO: conclusions

- If the problem has a single local optimum the power of RSO is not needed, although not dangerous
- Most real-world problems are infested with many locally optimal points
- RSO is crucial to **transform a local search building block into an effective and efficient solver.**
- RSO with prohibitions has been used for problems ranging from combinatorial optimization to the minimization of continuous functions and to sub-symbolic machine learning tasks

GIST

- Local search is a simple and very effective way to identify improving solutions for discrete optimization problems
- It generates a **sequence of changes, each change being local**
- Local search stops at **locally-optimal points** and the current search trajectory is trapped
- Additional **diversification** means are needed to escape from local attractors.

GIST (2)

- Reactive Search Optimization (RSO) uses **learning and adaptation during the optimization process**, to fine-tune the search technique to the current problem, task and local properties.
- An intelligent module overseeing the basic local search process
- It automatically balances **diversification** and **intensification**